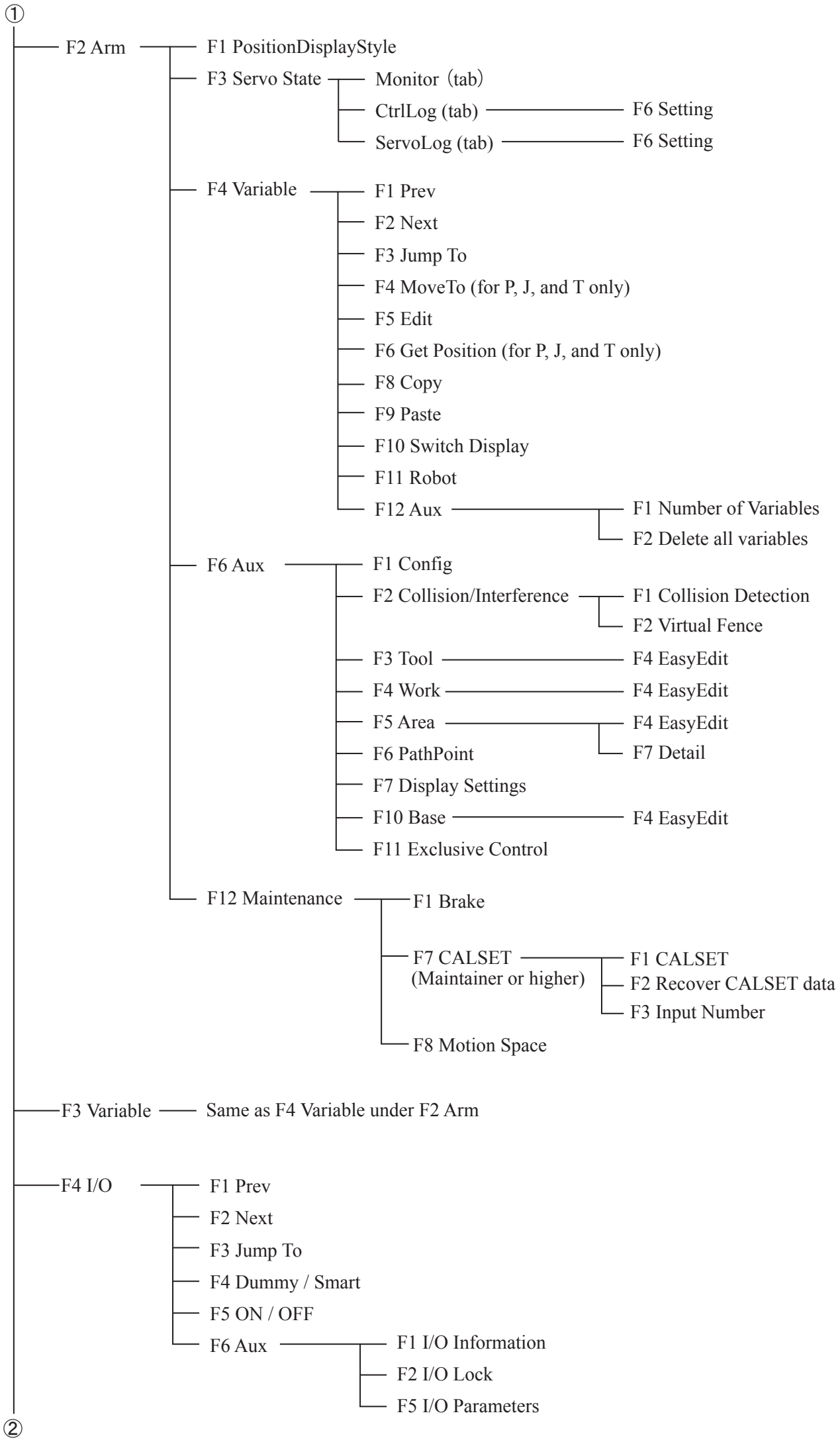
Top window

- F1 Program (Edit)
  - F1 New
  - F2 Delete
  - F3 Copy
  - F4 Paste
  - F5 Edit
    - F1 CreateNew
    - F2 Cut
    - F3 Copy
    - F4 Paste
    - F5 Edit
    - F6 Save & CheckSyntax
    - F7 Comment
    - F8 Uncomment
    - F9 Format
  - F6 Aux
    - F1 Program settings
      - Program (tab)
      - SupervisoryTask (tab)
    - F5 Program parameters
    - F7 Start Supervisory
    - F8 Stop Supervisory
    - F10 Delete all static variables
    - F11 Delete all programs
  - F9 Encrypt / Decrypt
  - F10 File Lock/Unlock
  - F11 Rename
  - F12 Check Syntax
- F1 Program (Run)
  - F1 Halt
  - F2 StepStop
  - F3 CycleStop
  - F4 Start
  - F6 StepStart
  - F7 Reset
  - F9 Priority
  - F10 Continue Start
  - F11 Display

①


①
F2 Arm
F1 PositionDisplayStyle
F3 Servo State
Monitor（tab）
CtrlLog (tab)
F6 Setting
ServoLog (tab)
F6 Setting
F4 Variable
F1 Prev
F2 Next
F3 Jump To
F4 MoveTo (for P, J, and T only)
F5 Edit
F6 Get Position (for P, J, and T only)
F8 Copy
F9 Paste
F10 Switch Display
F11 Robot
F12 Aux
F1 Number of Variables
F2 Delete all variables
F6 Aux
F1 Config
F2 Collision/Interference
F1 Collision Detection
F2 Virtual Fence
F3 Tool
F4 EasyEdit
F4 Work
F4 EasyEdit
F5 Area
F4 EasyEdit
F6 PathPoint
F7 Detail
F7 Display Settings
F10 Base
F4 EasyEdit
F11 Exclusive Control
F12 Maintenance
F1 Brake
F7 CALSET
(Maintainer or higher)
F1 CALSET
F2 Recover CALSET data
F3 Input Number
F8 Motion Space
F3 Variable
Same as F4 Variable under F2 Arm
F4 I/O
F1 Prev
F2 Next
F3 Jump To
F4 Dummy / Smart
F5 ON / OFF
F6 Aux
F1 I/O Information
F2 I/O Lock
F5 I/O Parameters
②

②

- F5 Panel
- F6 Setting
  - F1 Login
    - F5 Password change
  - F2 System Info
    - General (tab)
      - F6 VRC Setting
    - Robot (tab)
    - Controller(tab)
      - F1 Device info
      - F2 CPU info details
      - F3 Memory Info details
      - F4 Disc info details
  - F3 Pendant and Panel
    - F1 Language
    - F2 Pendant Setting
    - F3 Panel Settings
  - F4 Operation and Error Log
  - F5 Communication and Token
    - F1 Executable Token
    - F2 Network and Permission
    - F3 Data Communication
      - F5 Edit（For COM Selection）
      - F5 Edit（For Ethernet Selection）
      - F6 Set COM Port Number
    - F4 OPC-UA Server
    - F7 Ping
  - F6 Data Read and Write
    - F1 Project Read and Write
  - F7 Date and Maintenance
    - F1 Date and Maintenance
    - F2 Controller Battery
  - F8 Option
    - F1 Extension
    - F2 Program-Priority mode
    - F8 Version Up (Maintainer or higher)
    - F9 MCU VersionUp (Maintainer or higher)
    - F10 MCU Reset (Maintainer or higher)
  - F10 Cobotta
    - F1 RiskAssessor password
    - F2 Diagnosis
    - F4 Packing position
    - F6 Parameters
- F8 Vision
  - F1 Vision Calibration
  - F2 IP address Setting
  - F3 Administrator and Password
  - F7 Build-in Vision (license required)
- F9 Servo Hand
- F11 MessageLog